## Weak* topology and its application

M. Doležal, J. Grebík, J. Hladký, I. Rocha, and V. Rozhoň

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## Graphons and cut distance convergence



Represent graphs as adjacency matrices:


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But one has to be careful:


## Cut distance topology

1) Compare the number of edges inside any vertex set:

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d_{\square}(U, V)=\sup _{S, T \subseteq[0,1]}\left|\int_{S \times T} U(x, y)-V(x, y)\right|
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2) Minimise over permutations of the adjacency matrix:

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\delta_{\square}(U, V)=\inf _{\pi} d_{\square}\left(U, V^{\pi}\right) .
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where $\pi:[0,1] \rightarrow[0,1]$ runs over all measure preserving bijections and $U^{\pi}(x, y)=U(\pi(x), \pi(y))$.


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Lovász-Szegedy'06: For every sequence $U_{1}, U_{2}, \ldots$ there exist $\pi_{n_{1}}, \pi_{n_{2}}, \ldots$ and $V$ such that $U_{n_{1}}^{\pi_{n_{1}}}, U_{n_{2}}^{\pi_{n_{2}}}, \ldots \xrightarrow{d_{\square}} V$.

## Weak* convergence

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U_{1}, U_{2}, \ldots \xrightarrow{w^{*}} V \Longleftrightarrow \forall S, T \subseteq[0,1]: \lim _{n \rightarrow \infty} \int_{S \times T} U_{n}=\int_{S \times T} V .
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Observation: For every sequence $U_{1}, U_{2}, \ldots$ there exist $\pi_{n_{1}}, \pi_{n_{2}}, \ldots$ and $V$ such that $U_{n_{1}}^{\pi_{n_{1}}}, U_{n_{2}}^{\pi_{n_{2}}}, \ldots \xrightarrow{w^{*}} V$.

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## Weak* convergence: structuredness order



- The relation $\succeq$ is a preorder.
- $U \succeq V$ and $V \succeq U$ $\delta_{\square}(U, V)=0$
- Maximal elements are zero-one graphons, minimal are constant graphons.


## Weak* convergence: compatible parameters

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Suppose that $\Theta$ satisfies:

- $\Theta$ is continuous in $L_{1}$,
- $\Theta(U)=\Theta\left(U^{\pi}\right)$ for measure preserving bijection $\pi$,
- $\frac{1}{2} \Theta(U)+\frac{1}{2} \Theta(V) \geq \Theta\left(\frac{U+V}{2}\right)$.

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1) It suffices to show that the value of $\Theta$ does not increase after averaging any graphon on any partition, i.e., $\Theta\left(U^{\bowtie \mathcal{P}}\right) \leq \Theta(U)$. 2) Approximate $U^{\ltimes \mathcal{P}}$ by versions of $U$, i.e.,
$U^{\ltimes \mathcal{P}} \stackrel{L_{1}}{\approx} \frac{1}{n}\left(U^{\pi_{1}}+\cdots+U^{\pi_{n}}\right)$ and use convexity.

## Weak* convergence: compatible parameters

Note that the parameter $t(H, \cdot)$ is both continuous in $L_{1}$ and $t(H, U)=t(H, V)$ if $\delta_{\square}(U, V)=0$.

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t(H, U)=\int_{[0,1]^{|V(H)|}} \prod_{i j \in E(H)} U\left(x_{i}, x_{j}\right)
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A graph $H$ is called weakly norming, if $t(H, \cdot)^{1 /|E(H)|}$ is convex.

## Theorem (Hatami'10)

Hypercubes, complete bipartite graphs, even cycles,... are weakly norming, thus compatible. Nonbipartite graphs, nonstar trees,... are not weakly norming.

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A graph $H$ is called Sidorenko, if $t(H, \cdot)$ is minimised by constant graphons.
Each weakly norming graph is compatible with structuredness order and thus Sidorenko.

## Weak* convergence: compatible parameters

## Theorem (Král', Martins, Pach, Wrochna'18+)

There are edge-transitive graphs that are not compatible, thus not weakly norming

## Question (Král', Martins, Pach, Wrochna'18+)

Is it true that every connected graph $H$ is weakly norming if and only if it is compatible with structuredness order?

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We get $t(H, U)^{1 /|E(H)|}+t(H, V)^{1 /|E(H)|} \geq \frac{1}{4} t(H, U+V)^{1 /|E(H)|}$. Recover the constant loss via tensor power trick.

