

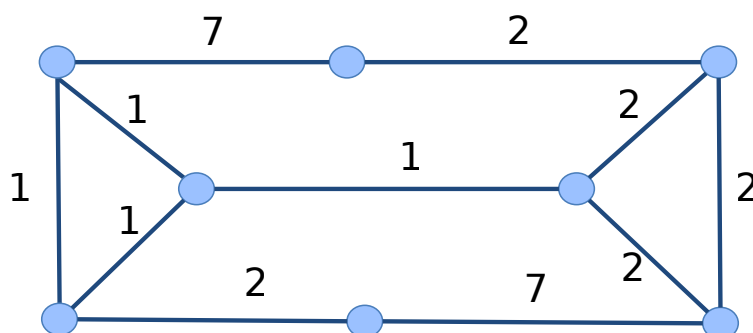
# INTRO TO APPROXIMATION, CLASS 2

the travelling salesman has come to us

From the last time:

**EXERCISE ONE** Simulate a biased coin with the probability of heads equal to  $p$  using a fair coin. It remains to deal with the case of arbitrary  $p \in (0, 1)$  (even irrational), while keeping the expected number of flips very small.

**EXERCISE TWO** Consider the following graph:



1. Find the shortest Hamiltonian cycle in this graph.
2. What is the optimal solution to the graph TSP problem on this graph?
3. What solution is found by a run of the Christofides' algorithm?

**EXERCISE THREE** Find an infinite class of graphs showing that the algorithm for metric TSP that uses a DFS traversal of the minimum spanning tree (and shortcuts) is no better than a 2-approximation.

More precisely, for infinitely many  $n$ 's construct a graph  $G_n$  with  $n$  vertices so that

$$\frac{\text{ALG}(G_n)}{\text{OPT}(G_n)} \rightarrow 2$$

for  $n \rightarrow \infty$  where  $\text{ALG}(G_n)$  is the cost of the algorithm's solution and  $\text{OPT}(G_n)$  is the optimum cost.

**EXERCISE FOUR** Consider a connected, directed graph  $G$  with edge lengths. Before studying the TSP problem on directed graphs, we can search for a more general structure – a subgraph  $P \subseteq G$  of minimum total length such that  $P$  contains all the vertices and every vertex has exactly one entering and one exiting edge. This problem is called **MINIMUM DIRECTED CYCLE COVER**.

- You can use a straightforward total unimodularity argument, if you know what that is from Optimization methods.
- If you are not familiar with total unimodularity, you can use a direct argument. You can for instance make use of the fact that minimum-weight perfect matching can be found in polynomial time. (Remember, Christofides' algorithm also uses this fact.)

EXERCISE FIVE      Is TSP solvable in polynomial time? One could suggest a dynamic programming algorithm as follows:

1. Create table  $d[i, x, y]$  where the meaning of the entry is „best walk from  $x$  to  $y$  in  $i$  steps“.
2. Set  $d[0, x, x] = 0$  and  $d[0, x, y] = \infty$ .
3. For every length  $i \in \{1, 2, 3, \dots, n\}$  :
4.            For every pair of vertices  $a, b$ :
5.                    Visit neighbors and set  $d[i, a, b] = \min_{x \text{ neighbor of } a}(d(a, x) + d[i - 1, x, b])$ .
6.                    Set  $d[i, b, a] = d[i, a, b]$ .
7. Return the minimum value  $d[n, v, v]$  over all  $v$ .

Analyze this algorithm.