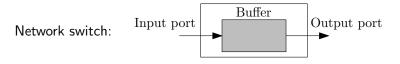
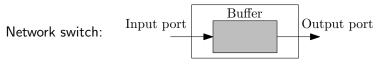
A ϕ -Competitive Algorithm for Scheduling Packets with Deadlines

Pavel Veselý University of Warwick

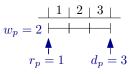
Joint work with Marek Chrobak (UC Riverside), Łukasz Jeż (Wrocław Univ.), and Jiří Sgall (Charles Univ., Prague).

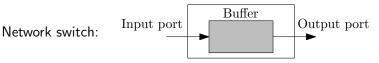
SODA'19, January 6



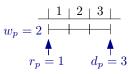


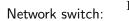
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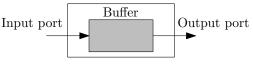




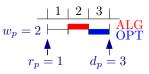
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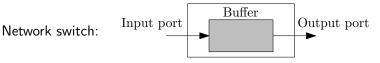




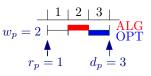


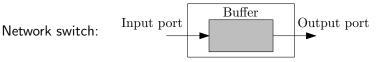
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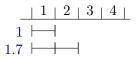


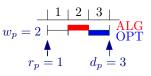
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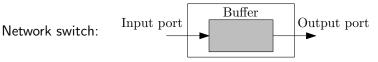




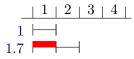
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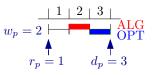


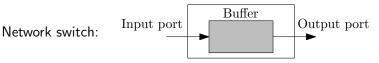




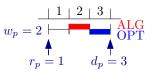
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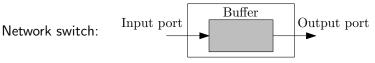




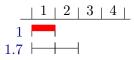
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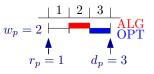


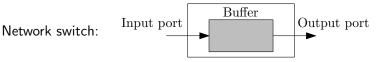
ONLINE PACKET SCHEDULING WITH DEADLINES



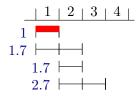
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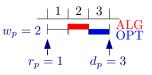


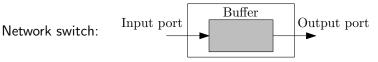




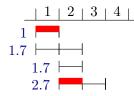
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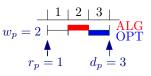


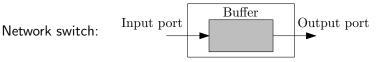




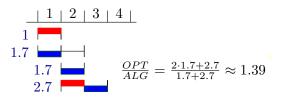
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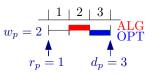


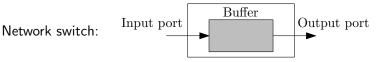




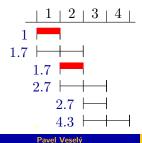
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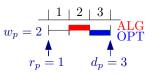


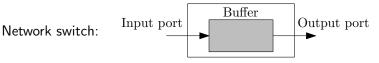




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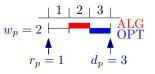






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Scheduling problem $1|online, r_j, p_j = 1| \sum w_j(1 - U_j)$ A.k.a. BUFFER MANAGEMENT IN QOS SWITCHES



Competitive ratio of online algorithms

• Algorithm is *R*-competitive if for any instance *I*

 $\mathsf{OPT}(I) \leq R \cdot \mathsf{ALG}(I)$

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- Game: the algorithm vs. an adversary
 - The adversary decides on further input to maximize OPT/ALG

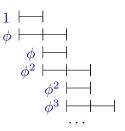


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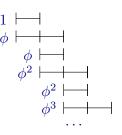
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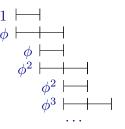
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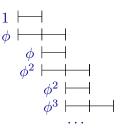
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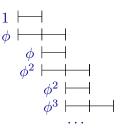


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- Optimal future profit unless new packets arrive
- Scheduled plans (a.k.a. provisional schedules) used already by

[Li et al. '05, Li et al. '07, Englert & Westermann '07]

$\mathsf{Plan}\ \mathcal{P}$

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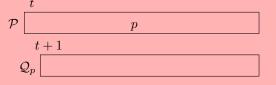
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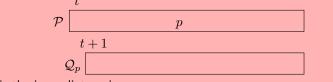
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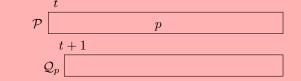
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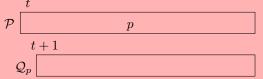
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Plan and its Structure

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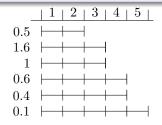
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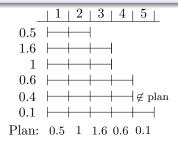
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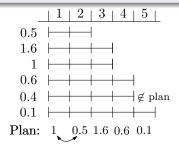
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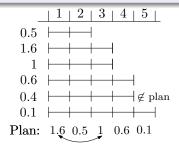
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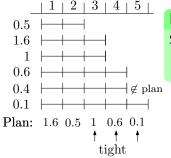
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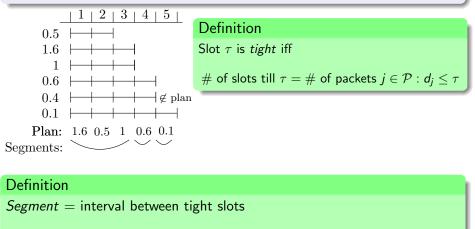
Definition

Slot τ is *tight* iff

$$\#$$
 of slots till $au = \#$ of packets $j \in \mathcal{P} : d_j \leq au$

$\mathsf{Plan}\ \mathcal{P}$

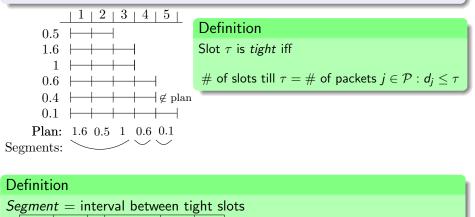
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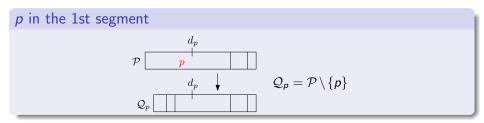
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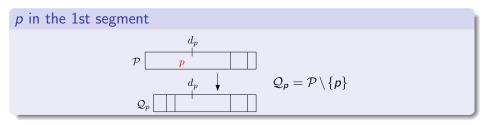
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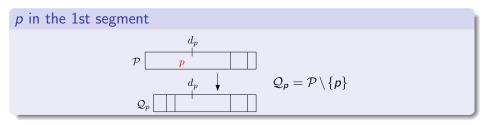


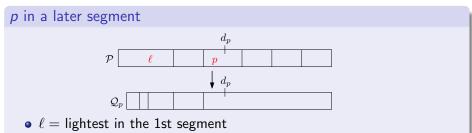


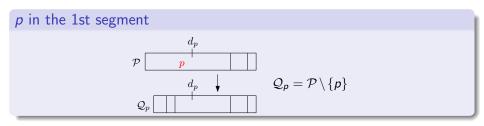


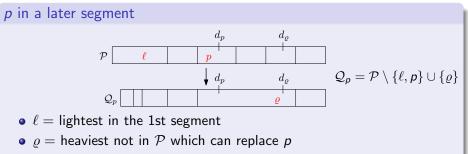


Pavel Veselý





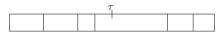




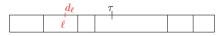
replacement packet for p

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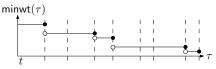
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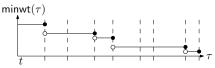
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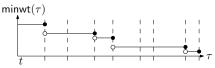
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$minwt(\tau)$ after plan updates

- for any fixed τ , minwt(τ) does not decrease:
 - after arrival of a new packet
 - after scheduling a packet from the 1st segment

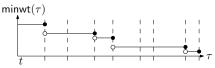
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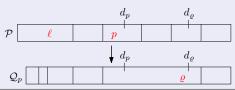
- for any fixed τ , minwt(τ) does not decrease:
 - after arrival of a new packet
 - after scheduling a packet from the 1st segment
- minwt(au) decreases for some au after sch. a packet from later segment

- $\mathsf{minwt}(au) = \mathsf{min}\text{-weight}$ in $\mathcal P$ that can be on a slot up to au
- = min-weight in \mathcal{P} till the next tight slot after τ



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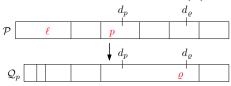


The problem:

$$arrho
ot\in \mathcal{P} \Rightarrow w_arrho < \mathsf{minwt}(d_arrho)$$

• Idea: modify $\text{LessGreedy}(\phi)$ so that $\min wt(\tau)$ never decreases

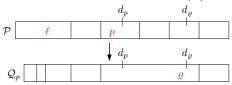
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The problem:

 $\varrho \not\in \mathcal{P} \Rightarrow w_{\varrho} < \operatorname{minwt}(d_{\varrho})$

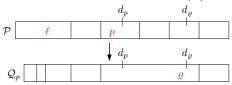
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The problem: $\varrho \notin \mathcal{P} \Rightarrow w_{\varrho} < \operatorname{minwt}(d_{\varrho})$

• \Rightarrow increase the weight of ϱ to minwt(d_{ϱ})

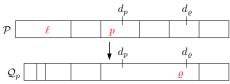
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The problem: $\varrho \notin \mathcal{P} \Rightarrow w_o < \operatorname{minwt}(d_o)$

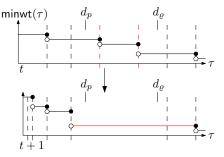
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- Not enough if segments merge:

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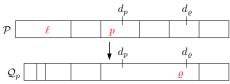


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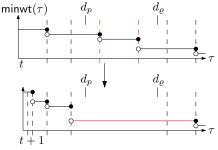


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- Not enough if segments merge:



• \Rightarrow avoid merging segments

Pavel Veselý

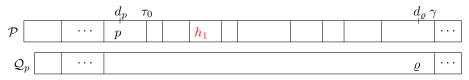
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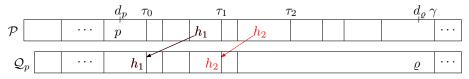
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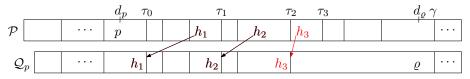
- h_1 = heaviest packet in $(\tau_0, \gamma]$,
- decrease deadline of h_1 to τ_0

- Schedule packet $p \in \mathcal{P}$ maximizing $\phi \cdot w_p + w(\mathcal{Q}_p)$
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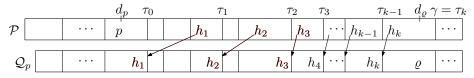
- h₂ = heaviest packet in (τ₁, γ],
- decrease deadline of h_2 to τ_1

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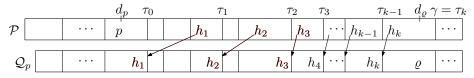
- h₃ = heaviest packet in (τ₂, γ],
- decrease deadline of h_3 to τ_2

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- for $i = 1, 2, \ldots$: h_i = heaviest packet in $(\tau_{i-1}, \gamma]$,
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- if $w_{h_i} < \minwt(\tau_{i-1})$, then increase weight of h_i to $\minwt(\tau_{i-1})$

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- Potential function

Amortization Techniques

- Increasing weights
- **2** Modifications of the adversary (optimal) schedule ADV
- Otential function

Potential function

Advantage of the algorithm over the adversary:

 ${\small \bigcirc} \ \mathcal{P} \setminus \mathsf{ADV} = \mathsf{packets} \text{ in the plan that the adversary will not schedule}$

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Invariant

• set
$$\mathcal{P} \setminus \mathsf{ADV} \cup \mathcal{F}$$
 is feasible

$m \geq 1$ packets sent in each step

- Our algorithm is $\phi pprox 1.618$ -competitive for any $m \ge 1$
- Best upper bound tends to $\frac{e}{e-1} \approx 1.58$ [Chin *et al.* '04]

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