

$$\langle p|q \rangle = \frac{1}{\sqrt{2\pi\hbar}} e^{-\frac{i}{\hbar} p q}$$

$$\langle p|x \rangle = \frac{1}{\sqrt{2\pi\hbar}} e^{-\frac{i}{\hbar} p x}$$

$$|Y\rangle \rightarrow \langle 1|Y\rangle = \int dx |x\rangle \langle x|Y\rangle = \int dx \psi(x) \langle x|Y\rangle$$

index  $\psi(x) \leftarrow$  "free" coefficient / spojit' koeficienty...

$$\begin{aligned} & \rightarrow \int dp |p\rangle \langle p|Y\rangle \\ & = \int dp |p\rangle \langle p| \int dx |x\rangle \langle x|Y\rangle \\ & = \int dp |p\rangle \int dx \langle p|x \rangle \langle x|Y\rangle \\ & = \int dp |p\rangle \int dx \frac{1}{\sqrt{2\pi\hbar}} e^{-\frac{i}{\hbar} p x} \psi(x) \\ & = \int dp |p\rangle \psi(p) \end{aligned}$$

$$\rightarrow \psi(p) = \frac{1}{\sqrt{2\pi\hbar}} \int dx e^{-\frac{i}{\hbar} p x} \psi(x)$$

$\rightarrow$  Gauss,  $\langle x \rangle \langle x^2 \rangle$

$$\psi(x) = \frac{1}{\sqrt{\pi}} e^{-\frac{x^2}{2}} \quad , \quad \text{width } \hbar, a, \omega \rightarrow \frac{1}{\sqrt{\pi} \sqrt{a}} e^{-\frac{x^2}{2a}}$$

$$\alpha = \sqrt{\frac{\hbar}{m\omega}}$$

$$\begin{aligned} \psi(p) & = \frac{1}{\sqrt{2\pi\hbar}} \int dx e^{-\frac{i}{\hbar} p x} \frac{1}{\sqrt{\pi} \sqrt{a}} e^{-\frac{x^2}{2a}} \\ & = \frac{1}{\sqrt{2\pi\hbar} \sqrt{a} \sqrt{\pi}} \int dx e^{-\frac{1}{2a^2} (x^2 + 2\frac{i}{\hbar} p x)} \end{aligned}$$

$$x^2 + 2\frac{i\alpha^2}{\hbar} p x$$

$$A=1 \quad B = \frac{i\alpha^2}{\hbar} p \quad C = -\frac{\alpha^2}{\hbar} p^2$$

$$\begin{aligned} & = \frac{1}{\sqrt{2\pi\hbar} \sqrt{a} \sqrt{\pi}} \int dx e^{-\frac{1}{2a^2} (x + \frac{i\alpha^2 p}{\hbar})^2} e^{-\frac{1}{2a^2} \frac{\alpha^2 p^2}{\hbar}} \\ & = \frac{1}{\sqrt{2\pi\hbar} \sqrt{a} \sqrt{\pi}} \int dx e^{-\frac{x^2}{2a^2}} e^{-\frac{\alpha^2 p^2}{2\hbar}} \end{aligned}$$

$$\begin{aligned} & = \frac{\alpha \sqrt{\pi}}{\sqrt{a} \sqrt{\pi} \sqrt{2\pi\hbar}} e^{-\frac{\alpha^2 p^2}{2\hbar}} = \sqrt{\pi} \cdot \alpha^2 = \alpha \sqrt{\hbar} \\ & = \frac{\sqrt{a}}{\sqrt{\pi} \sqrt{\hbar}} e^{-\frac{\alpha^2 p^2}{2\hbar}} \end{aligned}$$

$$\int e^{-Ax^2} = \sqrt{\frac{\pi}{A}}$$

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$$\psi(p) = \sqrt{\frac{\alpha}{4\pi\hbar}} e^{-\frac{\alpha^2 p^2}{4\hbar^2}}$$

Normalizer

$$\langle \psi | \psi \rangle = \frac{\alpha}{4\pi\hbar} \int_{-\infty}^{\infty} dp e^{-\frac{\alpha^2 p^2}{4\hbar^2}}$$

$$\int_{-\infty}^{\infty} e^{-Ax^2} = \sqrt{\frac{\pi}{A}} \quad A = \frac{\alpha^2}{4\hbar^2}$$

$$\Rightarrow = \frac{\alpha}{4\pi\hbar} \sqrt{\frac{\pi 4\hbar^2}{\alpha^2}} = 1 \text{ OK}$$

$$p = -i\hbar \frac{d}{dx}$$

$$\psi(x) = \frac{1}{\sqrt{2\pi\hbar}} e^{-\frac{x^2}{2a^2}}$$

$$\psi(p) = \frac{1}{\sqrt{4\pi\hbar}} e^{-\frac{\alpha^2 p^2}{4\hbar^2}}$$

$$\langle \psi(x) | p | \psi(x) \rangle = \int_{-\infty}^{\infty} dx \frac{1}{\sqrt{2\pi\hbar}} e^{-\frac{x^2}{2a^2}} (-i\hbar \frac{d}{dx}) \frac{1}{\sqrt{2\pi\hbar}} e^{-\frac{x^2}{2a^2}}$$

da für se  
da immer B

= 0 z immer diracke

$$\int_{-\infty}^{\infty} x^2 e^{-x^2} dx = \frac{3}{2} \sqrt{\frac{\pi}{A}}$$

$$\langle \psi(p) | p | \psi(p) \rangle = 0$$

$$\langle \psi(p) | p^2 | \psi(p) \rangle = \frac{\alpha}{4\pi\hbar} \int_{-\infty}^{\infty} p^2 e^{-\frac{\alpha^2 p^2}{4\hbar^2}} dp$$

$$= \frac{\alpha}{4\pi\hbar} \int_{-\infty}^{\infty} \sqrt{\frac{\pi 4\hbar^2}{\alpha^2}} \frac{\hbar^2}{2\alpha^2} = \frac{\hbar^2}{2\alpha^2} \checkmark$$

$$A = \frac{\alpha^2}{4\hbar^2}$$

$$\langle \psi(x) | p^2 | \psi(x) \rangle = \frac{(-i\hbar)^2}{2\pi\hbar} \int_{-\infty}^{\infty} e^{-\frac{x^2}{2a^2}} \frac{d^2}{dx^2} e^{-\frac{x^2}{2a^2}} dx$$

$$= \frac{-\hbar^2}{2\pi\hbar} \int_{-\infty}^{\infty} e^{-\frac{x^2}{2a^2}} \frac{d^2}{dx^2} \left( -\frac{2x}{2a^2} e^{-\frac{x^2}{2a^2}} \right) dx$$

$$= \frac{-\hbar^2}{2\pi\hbar} \int_{-\infty}^{\infty} e^{-\frac{x^2}{2a^2}} \left( -\frac{1}{a^2} + \frac{x^2}{a^4} \right) e^{-\frac{x^2}{2a^2}} dx$$

$$= \frac{\hbar^2}{2\pi\hbar} \int_{-\infty}^{\infty} e^{-\frac{x^2}{2a^2}} \left( \frac{1}{a^2} - \frac{x^2}{a^4} \right) dx$$

$$\int_{-\infty}^{\infty} x^2 e^{-x^2} dx = \frac{\sqrt{\pi}}{2}$$

$$= \frac{\hbar^2}{2\pi\hbar} \left[ \frac{1}{a^2} - \frac{1}{2a^2} \right] = \frac{\hbar^2}{2a^2} \checkmark \text{ OK}$$

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D. A:  $|\uparrow\rangle, |\downarrow\rangle$

B:  $|\uparrow\rangle, |\downarrow\rangle$

ce celkova' so'zre:  $|\uparrow\rangle_A |\uparrow\rangle_B, |\uparrow\rangle_A |\downarrow\rangle_B, |\downarrow\rangle_A |\uparrow\rangle_B, |\downarrow\rangle_A |\downarrow\rangle_B$   
 zjednoteni:  $|\uparrow\uparrow\rangle, |\uparrow\downarrow\rangle, |\downarrow\uparrow\rangle, |\downarrow\downarrow\rangle$

$\leftarrow \uparrow\uparrow\uparrow$

D. Vime  $S_z^A |\uparrow\rangle_A = \frac{1}{2} |\uparrow\rangle_A$

$S_z^B = S_z^A \otimes 1 + 1 \otimes S_z^B$

$S_z |\uparrow\rangle_A |\uparrow\rangle_B = S_z^A |\uparrow\rangle_A \otimes 1 |\uparrow\rangle_B + 1 |\uparrow\rangle_A \otimes S_z^B |\uparrow\rangle_B =$   
 $= \frac{1}{2} |\uparrow\uparrow\rangle + \frac{1}{2} |\uparrow\uparrow\rangle = |\uparrow\uparrow\rangle$ ;  $\frac{\langle \uparrow\uparrow | S_z | \uparrow\uparrow \rangle}{\langle \uparrow\uparrow | \uparrow\uparrow \rangle} = 1$   
 zrejara

$S_z |\uparrow\downarrow\rangle = \frac{1}{2} |\uparrow\downarrow\rangle - \frac{1}{2} |\uparrow\downarrow\rangle = 0$

$S_z |\downarrow\uparrow\rangle = 0 \rightarrow \langle \downarrow\uparrow | S_z | \downarrow\uparrow \rangle = 0$

$S_z |\downarrow\downarrow\rangle = -|\downarrow\downarrow\rangle \rightarrow \langle \downarrow\downarrow | S_z | \downarrow\downarrow \rangle = -1$

klasni stav B  
 diagonalni matrice

$S_z = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \leftarrow$  matrice  $S_z = S_z^A + S_z^B$

$S_z^A = S_z^A \otimes 1 + 1 \otimes S_z^B$   
 $\begin{pmatrix} 1/2 & 0 \\ 0 & -1/2 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1/2 & 0 \\ 0 & -1/2 \end{pmatrix}$   
 $\begin{pmatrix} 1/2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1/2 & 0 \\ 0 & -1/2 \end{pmatrix}$

$\begin{pmatrix} 1/2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \end{pmatrix} + \begin{pmatrix} 1/2 & -1/2 & 0 & 0 \\ 0 & 1/2 & -1/2 & 0 \\ 0 & 0 & 1/2 & 0 \\ 0 & 0 & 0 & -1/2 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1/2 & -1/2 & 0 \\ 0 & 0 & 1/2 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$

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III Pripitana

$S_z^A \otimes S_z^B \rightarrow | \uparrow \uparrow \rangle, | \uparrow \downarrow \rangle, | \downarrow \uparrow \rangle, | \downarrow \downarrow \rangle$  jsou státní vlastní stavy

$$S_z^A \otimes S_z^B | \uparrow \uparrow \rangle = \frac{1}{2} \cdot \frac{1}{2} | \uparrow \uparrow \rangle = \frac{1}{4} | \uparrow \uparrow \rangle$$

$$S_z^A \otimes S_z^B | \uparrow \downarrow \rangle = \frac{1}{2} \cdot (-\frac{1}{2}) | \uparrow \downarrow \rangle = -\frac{1}{4} | \uparrow \downarrow \rangle$$

$$S_z^A \otimes S_z^B | \downarrow \uparrow \rangle = (-\frac{1}{2}) \cdot (\frac{1}{2}) | \downarrow \uparrow \rangle = -\frac{1}{4} | \downarrow \uparrow \rangle$$

$$S_z^A \otimes S_z^B | \downarrow \downarrow \rangle = (-\frac{1}{2}) \cdot (-\frac{1}{2}) | \downarrow \downarrow \rangle = \frac{1}{4} | \downarrow \downarrow \rangle$$

$$\rightarrow \begin{pmatrix} \frac{1}{4} & & & \\ & -\frac{1}{4} & & \\ & & \frac{1}{4} & \\ & & & -\frac{1}{4} \end{pmatrix}$$

$$\left( \frac{1}{2} \otimes \frac{1}{2} \right) \otimes \begin{pmatrix} \frac{1}{2} & & & \\ & \frac{1}{2} & & \\ & & \frac{1}{2} & \\ & & & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & & & \\ & \frac{1}{2} & & \\ & & \frac{1}{2} & \\ & & & \frac{1}{2} \end{pmatrix} \otimes \begin{pmatrix} \frac{1}{2} & & & \\ & \frac{1}{2} & & \\ & & \frac{1}{2} & \\ & & & \frac{1}{2} \end{pmatrix} =$$

$$M = \sum_i S_i^A \otimes S_i^B$$

$$= S_x^A \otimes S_x^B + S_y^A \otimes S_y^B + S_z^A \otimes S_z^B$$

$$\frac{1}{4} \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 0 & & & \\ & 0 & & \\ & & 0 & \\ & & & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & 1 & \\ & & & -1 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & 1 & \\ & & & -1 \end{pmatrix}$$

$$= \frac{1}{4} \begin{pmatrix} 0 & 0 & 1 & \\ 0 & 1 & 0 & \\ 0 & 1 & 0 & \\ 1 & 0 & 0 & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 0 & 0 & -1 & \\ 0 & 1 & 0 & \\ -1 & 0 & 0 & \\ 0 & 1 & 0 & 0 \end{pmatrix} + \frac{1}{4} \begin{pmatrix} 1 & & & \\ & -1 & & \\ & & 1 & \\ & & & -1 \end{pmatrix}$$

$$= \frac{1}{4} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

↳  $| \uparrow \uparrow \rangle, | \downarrow \downarrow \rangle$  státní vlastní stavy  
 $| \uparrow \downarrow \rangle, | \downarrow \uparrow \rangle$  se míchají ±